Doctoral Dissertation

Thesis Title

Author Name
Technology

Thesis Title

Author Name

Thesis Title

Abstract

Abstract.

Acknowledgements

Acknowledgements.

Contents

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Chapter 1
Introduction

This is the introduction. Some theses might be cited [1, 2, 3].

Notice hyperrefs are enabled. This means references (to chapters, sections, figures, tables, algorithms, etc) are links, which can be clicked to navigate through the thesis. Also, backrefs are enabled, which means that references include "cited on page(s)" links.

Figure 1.1 contains a hat. Table 1.1 contains some stuff. Algorithm 1 is also shown.

1.1   Outline

The rest of this thesis is organised as follows.

Chapter 2 contains conclusions. Not many, but some. It is highly recommended that your own conclusions chapter be more developed.

1.2   Publications

Some of the work presented in this thesis has been published in a number of journal and conference papers, available at http://aass.oru.se.

- Item1. block1. block2.
- Item2. text for item 2.

Figure 1.1: Long caption. This figure shows a hat.

Algorithm 1 Constraint-based planning

Require: The first input.
Ensure: The output.

  1: function function-name(parameters)
  2:     First statement.
  3:     for Something. do
  4:        if A condition. then
  5:           Statement.
  6:        else
  7:           Statement.
  8:        end if
  9:        Statement.
10:     end for
11: end function

Table 1.1: Long caption. This is a table.

		Heading1	Heading2
Heading3	Heading5	Some stuff in a table.	Some stuff in a table.
	Heading6	Some stuff in a table.	Some stuff in a table.

Chapter 2
Conclusions

These are conclusions.

References

[1] Sören Larsson. An industrial robot as carrier of a laser profile scanner : Motion control, data capturing and path planning. PhD thesis, Örebro University, Department of Technology, 2008. (Cited on page 1.)

[2] Kevin LeBlanc. Cooperative Anchoring : Sharing Information about Objects in Multi-Robot systems. PhD thesis, Örebro University, School of Science and Technology, 2010. (Cited on page 1.)

[3] Marco Trincavelli. Gas Discrimination for Mobile Robots. PhD thesis, Örebro University, School of Science and Technology, 2010. (Cited on page 1.)